

CM30174 + CM50206

Intelligent Agents

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Negotiation / version 0.4



November 1, 2011

Authors/Credits for this lecture

- Chs. 14, 15 and 9 of “An Introduction to Multiagent Systems” [Wooldridge, 2009].

Content

- 1 Overview
- 2 Auctions
 - Auction patterns
 - Agent strategies
 - Combinatorial Auctions
- 3 Negotiation: strategies and protocols
 - Task-oriented Domains
 - Working Together
 - Contract Net Protocol
- 4 Summary

Content

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Reaching Agreements

- How do self-interested agents reach agreements?
- In an extreme case (zero sum encounter) no agreement is possible — but in most scenarios, a mutually beneficial agreement can be concluded
- The capabilities of **negotiation** and **argumentation** are central to the ability of an agent to reach such agreements.
 - Consider an offer as \vec{v}_i s.t. $v_i \in \mathbb{R}^n$
 - Valuation is then $\sum_{i=0}^n w_i v_i$ such that given a threshold value, a decision can be made
 - Simple negotiation requires each agent to change \vec{v}_i such that the valuation monotonically approaches the threshold
 - Argumentation is the process of one agent getting another to change its \vec{w}_i

Protocols and Strategies

- Negotiation is governed by a particular **mechanism**, or **protocol**.
- The mechanism defines the “rules of encounter” between agents.
 - Auctions are a large class of “useful” mechanisms
- **Mechanism design** is the process of designing mechanisms so that they have certain desirable properties.
- Given a particular protocol, how can a particular **strategy** be designed that individual agents can use?
 - What is the *dominant* strategy for a particular mechanism?

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Auctions

- An auction takes place between an agent known as the auctioneer and a collection of agents known as the bidders.
- The goal of the auction is for the auctioneer to allocate the good to one of the bidders.
- In most settings the auctioneer desires to maximise the price; bidders desire to minimise price.

Auction Parameters

- Goods can have:

private value OR public/
common value OR correlated
value

- Winner may pay:

first price OR second price OR n^{th} price

- Bids may be:

open cry OR sealed bid

- Bidding may be:

one shot OR ascending OR descending

English Auctions

- English auction characteristics:
 - first-price,
 - open cry,
 - ascending.
- Susceptible to:
 - Winner's curse
 - Shills
- Dominant strategy is for agent successively to bid a small amount more than the current highest bid until it reaches their valuation, then withdraw.

Dutch Auctions

- Dutch auctions characteristics:
 - open-cry
 - descending
 - auctioneer starts price at artificially high value;
 - auctioneer lowers offer price until some agent makes a bid equal to the current offer price;
 - the good is then allocated to the agent that made the offer.
- Best strategy is to bid only at own valuation

Sealed-Bid Auctions

- Sealed bid auction characteristics:
 - first-price
 - sealed-bid
 - one-shot
- Single round;
- Bidders submit a sealed bid for the good;
- Good is allocated to agent that made highest bid.
- Winner pays price of highest bid.
- Best strategy is to bid less than true valuation.

Vickrey Auctions

- Vickrey auctions characteristics:
 - second-price
 - sealed-bid
 - one-shot
- Good is awarded to the agent that made the highest bid; at the price of the second highest bid.
- Vickrey auctions susceptible to antisocial behavior: untruthful bids can distort market
- Bidding to your true valuation is dominant strategy in Vickrey auctions.
 - Overbid \rightsquigarrow risk of paying above valuation
 - Underbid \rightsquigarrow reduced chance of success

Continuous Double Auction

- Perhaps overlooked because it is simple, but it is also effective and the basis for many real-world mechanisms
- Given buyer B and seller S , proceed in rounds:
 - **Step 1:** The seller announces an offer price p_1
 - **Step 2:** The buyer announces a bid price p_2 , assume $p_1 > p_2$
 - **Step 3:** If $p_2 \geq p_1$, sale is agreed at $\frac{p_1+p_2}{2}$
 - **Step 4:** Seller *reduces* offer giving $p_i, i \in 3, 5, \dots$
 - **Step 5:** Buyer *increases* bid giving $p_j, j \in 4, 6, \dots$
 - Return to **Step 3**
- Description in terms of two agents, but readily adapts for multiple buyers and multiple sellers
- Example of a mechanism that is more generally applicable in an electronic than a physical setting.

Zero Intelligence Traders I

- Original idea set out in [Gode and Sunder, 1993]
- Trader submits random bids and offers
- Simulations using experimental CDA markets demonstrate the transaction price time-series is *human-like*:
 - Appearing to converge to the theoretical equilibrium price
 - Yielding allocative efficiency comparable to human markets
- Experiments with combinations of three kinds of agents:
 - ZI-U: unconstrained agents, settle at any price
 - ZI-C: constrained agents, may not make a loss
 - human agents

Zero Intelligence Traders II

- Conclusions:
 - No intelligence needed to trade in a CDA as long as not permitted to trade at a loss
 - Market structure ensures allocative efficiency—the ‘invisible’ hand? (Smith)
- [Cliff and Bruten, 1997] identified pathological market conditions for ZI traders, supported by empirical results, specifically:
 - 1 symmetric supply and demand
 - 2 flat supply
 - 3 flat supply and demand curves with excess supply
 - 4 flat supply and demand curves with excess demand
- ZI-C only converges to equilibrium price in case 1
- Need memory + adaptation for cases 2–4

Zero Intelligence Plus (ZIP)

- Augment ZI-traders with basic machine-learning mechanism
- ZIP traders adapt their profit margin on the basis of four factors:
 - whether an agent still needs to buy or sell
 - was the last quote an offer (seller) or a bid (buyer)
 - was the last quote accepted or rejected
 - was the last quote bigger or smaller than own quote
- At time t trader i calculates
 - the shout price $p_i(t)$ for a unit j with
 - limit price $\lambda_{i,j}$ using
 - profit-margin $\mu_i(t)$, such that $p_i(t) = \lambda_{i,j}(1 + \mu_i(t))$

ZIP profit margin algorithm

- For sellers:
 - 1 if last shout accepted at price q then
 - 1 any seller s_i whose $p_i \leq q$ raises its margin
 - 2 if last shout was a bid then any seller s_i whose $p_i \geq q$ lowers its margin
 - 2 else
 - 1 if last shout was an offer then any seller s_i whose $p_i \geq q$ lowers its margin
- For buyers:
 - 1 if last shout accepted at price q then
 - 1 any buyer b_i whose $p_i \geq q$ raises its margin
 - 2 if last shout was an offer then any buyer b_i whose $p_i \leq q$ lowers its margin
 - 2 else
 - 1 if last shout was a bid then any buyer b_i whose $p_i \leq q$ lowers its margin

ZIP Adaptation

- Adaptation arises from the alteration of the profit margin using the Widrow-Hoff “delta rule”, widely used in back-propagation: $A(t + 1) = A(t) + \Delta(t)$
- $\Delta(t)$ is the change in output, determined by the product of a **learning rate** β and the difference between $A(t)$ and the **desired output** at time t , denoted $D(t)$:
$$\Delta(t) = \beta(D(t) - A(t))$$
- if $D(t)$ is constant the update rule gives asymptotic convergence of $A(t)$ to $D(t)$ at a speed determined by β .
- When a trader has to change its profit margin, compute a **target price** $\tau_i(t)$ and use the Widrow-Hoff rule to compute the shout price at the next time step, $p_i(t + 1)$
- Full details in [Cliff and Bruten, 1997]

Combinatorial Auctions I

- Auctions supposed to achieve (economically) efficient, effective allocation
- Preceding mechanisms depend on “intelligent” and “rational” bidding
- But need **complete** information for a Pareto optimal allocation
- CA aims to achieve optimal allocation by putting all the decision making in the auctioneer, hence we have
- **The Winner Determination Problem**: given a set of bids in a CA, find an allocation of items (not necessarily all) to bidders to maximize revenue

Combinatorial Auctions II

- Revenue is maximized by the allocation that maximizes the sum over all bidders of the bidders' valuations for the subset of items they receive.
- Bids are specified as valuations for a subset of items—called a *bundle*
- WDP can be written as an integer linear program that is equivalent to the weighted set packing problem and hence NP-hard.
- Problem is hard because need to check for each subset of the bids whether the subset is feasible (no bids share items) and how much revenue results... For k bids, there are 2^k subsets.

Combinatorial Auctions II

- Example: given n items for sale (1,2,3,4,5,6,7,8,9)

Bidder	Bid	Bundle
1	45	1,2
2	98	1,4,7,8
3	86	9,4,5,1,2
4	62	9,4

- Looking at individual bids, the revenue from bid 2 is greatest
- But bids 1 and 4 are for non-overlapping bundles, and so can *both* be satisfied and maximizes revenue by selling elements 1,2,4,9 for 107 (45+62).

Combinatorial Auctions IV

- (Naïve) Algorithmic solution builds a matrix of all possible combinations, then searches for sets that generate the greatest utility.
 - Take first combination
 - Then examine any other combinations that
 - 1 match and
 - 2 have a higher score,until done
- Practical solvers essentially take the same approach, but have good heuristics for pruning the search tree.

Which auction?

- For bundles: CA is optimal, but not necessarily practical
- For simple encounters: CDA is effective
- Economic theory says there is no difference between the rest in general, although individuals may differ

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Negotiation

- Auctions good for resource allocation
- Need **negotiation** for reaching agreements
- Characteristics of a negotiation:
 - A **negotiation set**: possible proposals agents can make
 - A **protocol**: moves in the negotiation process
 - **Strategies**, individual and private to each agent
 - A **rule** is deal struck and what is it
- Negotiation usually proceeds in a series of rounds
- Each agent makes a proposal at each round

Negotiation scenario

- A delivery problem:
 - Agent A_1 has two goods, G_1 and G_2
 - Agent A_2 has two goods, G_3 and G_4
 - Goods G_1 and G_3 need to be delivered to location L_1 , and
 - Goods G_2 and G_4 to L_2
- Each good delivery problem is a task
- Worst case is that each agent goes to L_1 and L_2
- Better to exchange one task so one agent goes to L_1 and the other to L_2
- Task-oriented domains formalize this kind of problem

Task Oriented Domains

- A task-oriented domain (TOD) comprises:
 - $\mathcal{T} = t_1, \dots, t_m$: the set of tasks
 - $\mathcal{A} = a_1, \dots, a_n$: the set of agents
 - $c : 2^{\mathcal{T}} \rightarrow \mathbb{R}^+$ is cost of executing each subset of tasks, where $2^{\mathcal{T}}$ denotes all the finite subsets of \mathcal{T}
 - The cost function is *monotonic*: adding tasks never decreases the cost, i.e.

$$\mathcal{T}_i, \mathcal{T}_j \subseteq \mathcal{T} \text{ and } \mathcal{T}_i \subseteq \mathcal{T}_j \Rightarrow c(\mathcal{T}_1) \leq c(\mathcal{T}_2)$$

- An **encounter** is the assignment of an ordered list of tasks T_1, \dots, T_n , such that $T_i \in \mathcal{T}$, to agent $a_i \in \mathcal{A}$
- But can agent A_i do better by negotiating a reallocation of its tasks?

Deals in TODs

- Given agents $\{A_1, A_2\}$ and encounter $\langle T_1, T_2 \rangle$:
 - A **deal** allocates tasks $T_1 \cup T_2$ to agents a_1 and a_2
 - In $\delta = \langle D_1, D_2 \rangle$, agent a_i is allocated tasks D_i with no tasks left over: $D_1 \cup D_2 = T_1 \cup T_2$
 - The cost of the deal to agent a_i is $c(D_i)$
- The **utility** of deal δ to agent a_i :

$$\text{utility}_i(D) = c(T_i) - c(D_i)$$

- In the absence of (re-)allocation, agents take the **conflict deal**, $\Theta = \langle T_1, T_2 \rangle$:

$$\text{utility}_i(\Theta) = 0, \forall a_i \in \mathcal{A}$$

- Deal δ is **individual rational** if it has positive utility

Deal Dominance

- The deal $\delta_1 \succ \delta_2$ (dominates) iff:
 - C1: Deal δ_1 is at least as good as δ_2 for every agent:

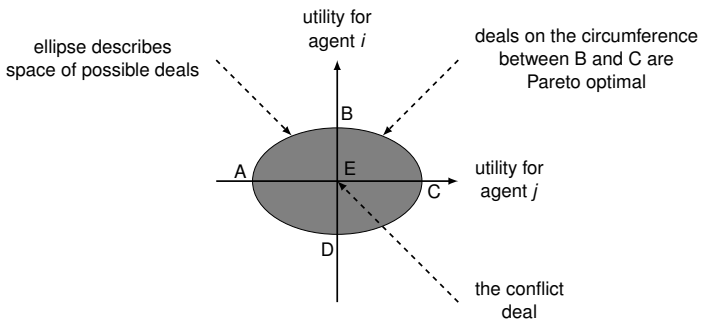
$$\bigwedge_{i=1}^n utility_i(\delta_1) \geq utility_i(\delta_2)$$

- C2: Deal δ_1 is better than δ_2 for some agent:

$$\bigvee_{i=1}^n utility_i(\delta_1) > utility_i(\delta_2)$$

- A deal $\delta_1 \succeq \delta_2$ (**weakly dominates**) if at least C1 holds
- A deal is **Pareto optimal** if $\nexists \delta_j$ such that $\forall j \delta_j \succ \delta_i, j \neq i$
- A deal δ is **individual rational** if $\delta \succeq \Theta$
- The **negotiation set** is the set of deals that are:
 - individual rational *and*
 - Pareto efficient

The negotiation set



- ABCD = possible deals
- $utility(E) >$ all deals left of B-D for agent j
- $utility(E) >$ all deals below A-C for agent i

The Monotonic Concession Protocol

- Negotiation proceeds in rounds
 - 1 Round 1: agents simultaneously propose a deal from the negotiation set
 - 2 Agreement if one agent finds that the deal proposed by the other is at least as good or better than its proposal
 - 3 Otherwise, a new round of simultaneous proposals
 - 4 At each round, no agent may propose a deal is less preferred by the other agent than previously, i.e. utility must increase
 - 5 If neither agent makes a concession, then negotiation terminates with the conflict deal.

The Zeuthen Strategy

Three questions:

- What should an agent's first proposal be?
Its most preferred deal
- On any given round, who should concede?
The agent least willing to risk conflict.
- If an agent concedes, then how much should it concede?
Just enough to change the balance of risk.

Willingness to Risk Conflict

- Suppose agent has conceded a lot, then:
 - Its proposal is close to conflict deal
 - If conflict deal occurs, it is not much worse off
 - Therefore, it is willing to risk conflict
- Propensity to risk conflict rises as $\text{utility}(\delta) - \text{utility}(\Theta) \rightarrow 0$

Nash Equilibrium

The Zeuthen strategy is in Nash equilibrium: if one agent uses Zeuthen, the other cannot do better than use the same itself...

- Important for the design of automated agents
- No need for secrecy about strategy
- Situation cannot be exploited by using a different strategy

Returning to the scenario

- The tasks are: $T_1 = G_1 \rightarrow L_1$ $T_2 = G_2 \rightarrow L_2$
 $T_3 = G_3 \rightarrow L_1$ $T_4 = G_4 \rightarrow L_2$
- With encounter $\langle \{T_1, T_2\}, \{T_3, T_4\} \rangle$
- Let $c(T_1) = 5 + 4$ and $c(T_2) = 5 + 4$
- For $\delta_1 = \langle \{T_1, T_3\}, \{T_2, T_4\} \rangle$, let $c(T_1) = 5$ and $c(T_2) = 4$
- Hence $utility_1(\delta_1) = 9 - 5 = 4$ and $utility_2(\delta_1) = 9 - 4 = 5$
- Thus δ_1 is individual rational
- and Pareto optimal
- as is $\delta_2 = \langle \{T_2, T_4\}, \{T_1, T_3\} \rangle$

Collaboration

- Why and how to get agents work together? Motivations:
 - task sharing: components of a task are distributed to competent agents
 - result sharing: information (partial results etc) is distributed.
- Two scenarios: benevolent and self-interested

Benevolent Agents

- If we “own” the whole system, we can design agents to help each other whenever asked.
- Can assume agents are benevolent: our best interest is their best interest.
- Problem-solving in benevolent systems is cooperative distributed problem solving (CDPS).
- Benevolence simplifies the system design task enormously!

Self-Interested Agents

- If agents represent individuals or organisations, (the more general case), then cannot assume benevolence
- Assume agents to act to further their own interests, possibly at expense of others
- Potential for conflict.
- May complicate the design task enormously.
- Contract net: mechanism for cooperation among self-interested agents

Contract Net Protocol

- Basic contract net protocol:
 - 1 Recognition: agent cannot or prefers not to work alone
 - 2 Announcement:
 - Description of task itself (maybe executable)
 - Any constraints (e.g., deadlines, quality constraints).
 - Meta-task information (e.g., “bids must be submitted by... ”)
 - 3 Bidding:
 - Can agent complete task?
 - Assess quality constraints and price
 - 4 Awarding + expediting
 - Initiator evaluates bids and awards contract
 - Broadcast decision to bidders
 - Successful contractor then carries out task
- Variants:
 - Recursive: potential bidder issues a CFP etc.
 - Iterated: do not reject bids, but negotiate deals

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Summary

- Conventional auctions
- Zero Intelligence Traders
- Combinatorial auctions
- Task Oriented Domains
- Contract net protocol

Recommended Reading

- “An Introduction to Multiagent Systems” [Wooldridge, 2009]:
 - Chapter 6, 7 and 9
 - Chapter 14, pp299-310, combinatorial auctions
- Two papers [Bigham and Du, 2003] and [Bussmann and Schild, 2000] illustrate applications of negotiation
- Cramton [Cramton et al., 2005] examines combinatorial auctions in exhaustive detail, wherein Lehmann and Sandholm [Lehmann et al., 2005] discuss the Winner Determination Problem.
- [Zlotkin and Rosenschein, 1993] is the original TOD paper.
- [Cliff and Bruten, 1997] describes ZIP traders.

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